



IEEE Intelligent Transportation Systems Conference – ITSC 2026

**Convention Bureau Stazione Marittima
Naples, Italy
15 – 18 September 2026**





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IEEE Intelligent Transportation Systems Conference – ITSC 2026

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IEEE ITSC 2026

Institutional Greetings and Welcome Messages

Welcome to Campania

Message from the Vice President of the Campania Region, Regional Minister for Transport, Mobility and the Sea



Dear Participants,

It is a great honour and a genuine pleasure to welcome you to Naples and to the Campania Region on the occasion of the 29th IEEE International Conference on Intelligent Transportation Systems, hosted in Italy for the first time in the history of this prestigious conference.

The choice of venue could not be more meaningful. The Stazione Marittima, overlooking the Gulf of Naples, has for generations been a gateway between our city and the world: a place where people, goods, and ideas have always been on the move. There is no better setting for the world's leading scientific community devoted to the future of transportation.

Mobility is at the very heart of our regional agenda. Campania is engaged in an ambitious programme of investment in its transport system: the renewal of the regional railway fleet, the extension of the metro network, the transition to electric and low-emission public transport, the modernisation of our ports, and the digitalisation of services for citizens and travellers. In each of these efforts, the technologies discussed at this conference — intelligent, connected, cooperative, and sustainable transportation systems — are not an abstraction: they are the tools with which we intend to improve the daily life of millions of citizens, students, commuters, and visitors.

For this reason, the dialogue between the research community, industry, and public institutions is invaluable to us. The ideas presented in these days in Naples will help shape the policies and infrastructure of tomorrow, in Campania and far beyond.

I also warmly invite you to take some time to discover our region, and I am confident that the renowned hospitality of our land, together with its extraordinary cultural and culinary heritage, will make your stay memorable.

On behalf of the Regional Government of Campania, I extend my best wishes to the organisers, the IEEE Intelligent Transportation Systems Society, and all of you for a most successful and inspiring conference.

Welcome to Naples, welcome to Campania!

Mario Casillo

Vice President of the Campania Region

Regional Minister for Transport, Mobility and the Sea

Welcome to IEEE ITSC 2026

Message from the ITSC 2026 General Chair and Program Chair



Dear Colleagues,

On behalf of the Organizing Committee, it is our great pleasure to welcome you to the 29th IEEE International Conference on Intelligent Transportation Systems (IEEE ITSC 2026) in Naples, Italy.

IEEE ITSC 2026 marks a historic milestone: for the first time since the conference series was established, the flagship conference of the IEEE Intelligent Transportation Systems Society is being held in Italy. We are honored that Naples - a UNESCO World Heritage city and a centuries-old crossroads of cultures, innovation, and knowledge - has been chosen to host this memorable edition.

First and foremost, we thank you for your continued commitment to the IEEE ITSC community. Your research, innovations, and practical contributions have made ITSC the premier international forum for advancing intelligent transportation systems and shaping the future of safe, connected, automated, and sustainable mobility.

Organizing IEEE ITSC 2026 has been a truly collaborative effort. We sincerely thank the IEEE ITSS Conferences Standing Committee, the Technical Program Committee, Associate Editors, Reviewers, Organizing Committee, and the many volunteers whose dedication and professionalism have made this conference possible.

The technical program has been built through a rigorous peer-review process to ensure the highest scientific quality while covering the latest advances in Intelligent Transportation Systems. Alongside keynote lectures, regular and invited sessions, workshops, tutorials, demonstrations, and special sessions, IEEE ITSC 2026 strengthens its connection with industry through a dedicated Industry Track. Papers reporting industrial contributions are included in regular and invited sessions together with scientific papers, creating new opportunities for dialogue between researchers, technology developers, and industrial leaders to accelerate innovation and real-world deployment.

Beyond its outstanding technical program, IEEE ITSC 2026 is a conference built around people and community. We encourage you to take part in the networking activities, social events, and cultural experiences that make ITSC a unique opportunity to build collaborations, exchange ideas, and create lasting friendships.

This edition also introduces several exciting initiatives for students and early-career researchers. We proudly launch the IEEE ITSC Hackathon, inviting multidisciplinary teams to tackle real-world mobility challenges through creativity and innovation. The Late Breaking Results Poster Session offers an additional venue for presenting emerging research, while the Talent Portal & CV Booklet connects students, young professionals, researchers, and employers, fostering career opportunities and stronger academia-industry collaboration. Dedicated activities for Young Professionals,

Women in Engineering (WIE), and students further demonstrate our commitment to an inclusive, dynamic, and vibrant ITS community.

Whether you are presenting your research in a regular or invited session, leading a workshop or tutorial, attending inspiring plenary lectures, showcasing innovative technologies through demonstrations, participating in the Hackathon or the Late Breaking Results Poster Session, engaging with the Industry Track, exploring career opportunities through the Talent Portal, or simply reconnecting with colleagues from around the world, we hope IEEE ITSC 2026 will provide an inspiring environment where scientific excellence, innovation, collaboration, and friendship come together.

Thank you for being part of this historic first Italian edition of IEEE ITSC. We wish you a rewarding conference and an unforgettable stay in Naples.

Stefania Santini

The ITSC 2026 General Chair

Simona Sacone

The ITSC 2026 Program Chair

IEEE ITSC 2026

About the ITSC 2026 Logo



Naples has been a gateway between civilizations for more than two millennia. Founded by the Greeks and shaped by centuries of cultural exchange across the Mediterranean, the city has always connected people, ideas, and innovation. Today, this enduring spirit of connectivity is reflected in the mission of the IEEE Intelligent Transportation Systems Conference, where researchers and practitioners come together to shape the future of intelligent mobility.

- **The Bay of Naples:** The flowing blue line represents the Gulf of Naples, embracing the city and symbolizing the continuous movement of people, goods, and information. Like the sea that has connected cultures throughout history, it reflects the global exchange of knowledge fostered by the IEEE ITS community.
- **Mount Vesuvius:** The stylized profile of Mount Vesuvius, one of the world's most iconic landmarks, represents the identity, resilience, and energy of Naples. It reminds us that innovation flourishes where history, nature, and human ingenuity meet.
- **The Mediterranean Horizon:** The horizontal line evokes both the city's seafront and a transportation corridor extending toward the horizon. It symbolizes the infrastructures that connect communities through intelligent, safe, and sustainable transportation systems.
- **Castel dell'Ovo and the Legend of Parthenope:** The stylized silhouette of Castel dell'Ovo represents one of Naples' most iconic landmarks. Built on the islet of Megaride, the castle stands where, according to Greek mythology, the siren Parthenope came to rest after her song failed to enchant Ulysses. The Roman poet Virgil later enriched the legend by telling of a magical egg hidden within the castle's foundations, believed to protect both the fortress and the city. In the IEEE ITSC 2026 logo, Castel dell'Ovo symbolizes Naples' rich cultural heritage, resilience, and enduring spirit of hospitality, welcoming the global Intelligent Transportation Systems community to a city where history and innovation have always converged.
- **The Colors:** The shades of blue recall the Mediterranean Sea and the clear Neapolitan sky while reflecting the IEEE visual identity. Together, they express trust, technology, and openness to international collaboration.

Together, these elements represent the meeting of **heritage and innovation**, where one of the world's oldest cities becomes a place for advancing the next generation of intelligent transportation systems. Just as the Gulf of Naples embraces the city, **IEEE ITSC 2026** embraces a global community united by a common vision: creating safer, smarter, and more sustainable transportation systems. Naples welcomes researchers, engineers, practitioners, and students from around the world to shape the future of mobility while experiencing the timeless beauty and culture of the Mediterranean.

ITSC 2026

Keynote Speakers

Shengbo Eben Li

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Reinforcement Learning Algorithms for Complex System Control

Abstract

Reinforcement learning (RL) is a prominent branch of artificial intelligence, achieving remarkable success across various domains. This talk offers a systematic introduction of RL in complex control tasks, covering its design principles and mainstream algorithms, as well as its applications in self-driving car and legged robot. How to address critical challenges in real-world deployment will be discussed, such as enforcing safety constraints, mitigating training divergence, and improving sample efficiency. Three recent advancements in algorithm design will be introduced, including: (1) distributional soft actor-critic (DSAC) algorithm, which mitigates value overestimation and achieves state-of-the-art policy performance; (2) relativistic adaptive gradient descent (RAD) algorithm, which preserves symplecticity to ensure long-term training stability; (3) diffusion actor-critic with entropy regulator (DACER) algorithm, which endows the policy with the capability of multi-modal action distributions. These contributions aim to advance the development of robust and efficient RL for real-world autonomous systems.

Short Bio

Shengbo Eben Li is currently a full professor at Tsinghua University. His active research interests include automotive control systems, embodied intelligence, deep reinforcement learning, optimal control and optimal filtering, etc. He is the author of over 250 peer-reviewed papers, including best conference/journal papers (finalists) of IEEE ITSC, IEEE IVS, IET ITS, ICCAS, IFAC MECC, CAA CVCI, IEEE ICUS, CCCC, IEEE ITSM, L4DC, etc. Dr. Li has received over 20 prestigious academic awards, including Youth Sci. & Tech Award of Ministry of Education, Natural Science Award of Chinese Association of Automation, and National Award for Progress in Sci & Tech of China, etc. He was a member of Board of Governor of IEEE ITS Society and has served in numerous editorial roles, including as Senior AE of IEEE OJ ITS, and AEs of IEEE CST, IEEE ITSM, IEEE TITS, IEEE TIV, IEEE TNNLS, etc. He has authorized and co-authorized 5 academic books in Springer and IET Publisher. One of his recent books is Reinforcement Learning for Sequential Decision and Optimal Control (Springer, 2023).

Antonella Ferrara

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Multi-scale Traffic Control for Intelligent, Connected and Sustainable Next-Generation Mobility

Abstract

The impact of successful research in road traffic control spans across various domains, including the scientific, technological, social, and economic spheres. Its significance is profound, as it directly influences safety, quality of life, climate neutrality, energy resource utilization, and transportation costs. However, the development of effective methods and algorithms for road traffic control encounters notable methodological challenges. Traditionally, traffic control strategies have relied on infrastructure-based approaches. Yet, the rapid advancements in automotive technologies, traffic sensors, data processing, and communication have created unprecedented opportunities for the exploitation of an advanced type of vehicles, called connected and automated vehicles (CAVs), offering innovative solutions to longstanding traffic control challenges. This lecture will address these challenges and advancements, beginning with an overview of classical traffic control concepts. It will then focus on emerging research trends that exploit the multi-scale nature of traffic systems, from the microscopic scale of the individual CAV to the macroscopic scale of the traffic flow. Furthermore, the lecture will illustrate how efficiently controlled fleets of electric CAVs can be harmonized with the electric grid, fostering a synergistic integration between traffic and energy systems, and yielding societal benefits that extend well beyond those traditionally associated with traffic control.

Short Bio

Antonella Ferrara received the M.Sc. degree in Electronic Engineering and the Ph.D. degree in Electronic Engineering and Computer Science from the University of Genoa, Italy, in 1987 and 1992, respectively. Since 2005, she has been Full Professor of Automatic Control at the University of Pavia, Italy. Her research activities are mainly in the area of nonlinear control with application to traffic control, automotive systems, robotics and power grids. She is author and co-author of more than 450 publications including more than 175 journal papers, 2 monographs (published by Springer Nature and SIAM, respectively) and one edited book (IET). She is currently serving as Senior Editor of the IEEE Open Journal of Intelligent Transportation Systems and Associate Editor of Automatica. She served as Senior Editor of the IEEE Transactions on Intelligent Vehicles, as well as Associate Editor of the IEEE Transactions on Control Systems Technology, IEEE Transactions on Automatic Control, IEEE Control Systems Magazine and International Journal of Robust and Nonlinear Control. Antonella Ferrara is a member of the Long Range Planning Committee of the IEEE Intelligent Transportation Systems Society. She is the Chair of the EUCA Conference Editorial Board, the

Director of Operations of the IEEE Control Systems Society, the Vice-Chair for Industry of the IFAC TC on Nonlinear Control Systems (2024-2026), and a member of the IFAC Industry Board. She is also a member of the IFAC Conference Board, by virtue of her appointment as one of the two Program Chairs of the 24th IFAC World Congress to be held in Amsterdam, The Netherlands, in 2029. Among several awards, she was a co-recipient of the 2020 IEEE Transactions on Control Systems Technology Outstanding Paper Award. She is a Fellow of IEEE, Fellow of IFAC, Fellow of the European Academy of Sciences (EurASc) and Fellow of AAIA. She is also a Senior Fellow of the Brussels Institute for Advanced Studies (BrIAS).

Christian Merkt

**Director EU Governmental Affairs
Digitalisation and Automated Driving at
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Advancing Connected, Cooperative and Automated Mobility: CCAM Partnership Achievements and Contributions to Standardization

Abstract

The European CCAM Partnership brings together industry, research, and public stakeholders to accelerate the deployment of connected, cooperative and automated mobility across Europe and beyond. This talk presents the Partnership's mission, major achievements, and its role in fostering innovation and large-scale testing within real-life environments. Emphasis will be placed on the knowledge exchange mechanisms established across projects, which facilitate collaboration, avoid fragmentation, and accelerate the uptake of CCAM solutions. In addition, the presentation will highlight how CCAM project results are feeding into international standardization bodies, ensuring interoperability, safety, and global impact. By showcasing success stories, lessons learned, and ongoing initiatives, this contribution aims to stimulate dialogue within the intelligent transportation systems community and strengthen cooperation across regions and domains for the benefit of future mobility.

Short Bio

Christian Merkt has been the Director EU Governmental Affairs Digitalization and Automated Driving at BMW and CCAM Association Chair since 2024. He joined BMW 1999 and has since held several positions such as - most recently - Senior Expert Consumer Protection Vehicle Safety Asia with corresponding strategy of vehicle projects including coordination of research of Passive and Active Safety projects. During 2011-2014 he was Representative of the BMW GROUP Research and Innovation Center to the EU Institutions and supported various initiatives of Electromobility, ITS and Digitalization in the Automotive Sector. From 2006, Christian Merkt served as homologation engineer for the EU type approval of various BMW models as well as for small series electric vehicles. From 1999 to 2006, he initially worked at the BMW plant in Munich in the area of management systems for environmental protection and occupational safety.

Alberto Broggi

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Pier Paolo Porta

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Boosting Autonomous Driving Technology for Deployment at Scale

Abstract

We present a vertically integrated autonomous driving platform that combines custom silicon, sensing technologies, AI software, and large-scale data infrastructure into a unified potentially end-to-end solution. Designed to support the large-scale deployment of autonomous vehicles, the platform has been developed entirely in-house through more than a decade of research, validation, and real-world operation. At the core of the system is a domain-specific system-on-chip (SoC) that delivers high computational performance with exceptional energy efficiency, enabling sustained real-time operation in air-cooled environments. The hardware architecture is tightly co-designed with a complete autonomous driving software stack and includes dedicated accelerators for perception, multi-modal sensor fusion, trajectory planning, and vehicle control. Beyond onboard computing, a key pillar of the technology is a proprietary data and development infrastructure supporting large-scale data acquisition, automated annotation, dataset generation, model training, validation, and deployment. Through configurable sampling strategies and task-specific data recipes, the platform enables the systematic creation of balanced datasets for scalable and reliable neural-network development. This toolchain has been designed to address rare events and long-tail scenarios that are critical for real-world autonomous driving performance. This work illustrates how deep vertical integration, from custom silicon and proprietary radar technology to AI software, data infrastructure, and deployment tools, can provide the foundation for scalable autonomous driving systems. By jointly optimizing hardware, sensing, learning, and development workflows, the platform delivers an ecosystem designed for efficiency, reliability, continuous evolution, and large-scale deployment.

Short Bios

Alberto Broggi is the General Manager at VisLab (a spinoff of the University of Parma, acquired by Ambarella, Inc. in 2015) and previously a professor of computer engineering at the University of Parma in Italy. Widely considered a leading pioneer in the use of machine vision for automotive applications, Broggi has been actively engaged in autonomous driving research and development for over twenty-five years. He is both an IEEE and IAPR Fellow, was awarded two European Research Council (ERC) recognitions for his contributions to the development of perception for autonomous driving, and in 2017 was honored with the IEEE Medal for Environmental and Safety Technologies “for leadership in vehicular environmental perception, and for setting worldwide milestones in safe and reliable intelligent vehicles.” In 2018, Popular Mechanics called Broggi’s patent for a self-driving car one of the “15 Patents That Changed the World.”

Pier Paolo Porta was born in Fidenza, Italy on May 25th, 1980. In July 2005, he earned a Dr. Ing. (Masters) degree in Electronic Engineering from the Università di Parma, Italy. Also in 2005, he joined VisLab, the Artificial Vision research group at the Università di Parma, where, in 2010, he earned a PhD in Information Technology. In 2009, Porta became one of the founding associates of the VisLab srl spinoff. From 2010, he was on the Board of Governors for the company until it merged with Ambarella in 2015. He is now a Marketing Director responsible for Ambarella’s automotive European business as well as AD stack product marketing. Porta’s background is in autonomous driving and ADAS, with deep technical expertise in stereovision, sensor fusion and traffic-sign recognition. He took part in the DARPA Grand Challenge, as a member of the VisLab team in 2005 and 2007. Additionally, he participated in the VIAC project in 2010 and the PROUD project in 2013. Porta is the author of numerous papers that have been published in international scientific journals and conference proceedings.

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ITSC 2026

Types of Contributions

Workshops

The first day of the conference, **15 September 2026**, is dedicated to workshop presentations. The workshops are organized into parallel sessions taking place in the morning, during the lunch period, and in the afternoon.

The full list of accepted workshops is provided in the table below.

ID	Title	Proposers
W1	The 16th Workshop & Industry Panel on Cooperative and Automated Driving and Future Mobility	Meng Lu
W2	Socially Compliant and Strategic Autonomous Driving	Chen Sun, Dongpu Cao, Yang Xing, Yukun Lu, Saide Zhu, Chao Huang, Hong Wang, Guoshun Cai
W3	Next Generation Digital Railways: Connected, Automated, and Trustworthy Rail Transportation	Francesco Flammini, Anna Lina Ruscelli
W4	Introducing the Next Level of Driving Assistance Systems on the Roads: Today's Challenges	Eduardo Nebot, Julie Stephany Berrio Perez, Mao Shan, Stewart Worrall
W5	4th Workshop on Internet of Things in Intelligent Transportation Systems	Hyunsoo Yun, Can Cui, Seyhan Ucar, Yongkang Liu, Ziran Wang
W6	Compiler Safety and Verification for Intelligent Transportation Systems: From C/C++ to Rust	Kangwon Lee
W7	Next-Generation Maritime Operations	Laura Voggesberger, Jason Lin
W8	Autonomous Vehicles and Shared Mobility: Driving the Next Evolution of Intelligent Transportation	Irene Martínez, Vasso Reppa, Sergio Grammatico
W9	Interaction-driven behavior prediction and planning for autonomous vehicles	Sascha Hornauer, Eike Rehder, Jiachen Li, Maximilian Naumann, Wei Zhan, Martin Lauer, Masayoshi Tomizuka, Arnaud de La Fortelle, Christoph Stiller
W10	Open Automated Driving: Collaborative Development Framework and Benchmark-Driven Evaluation	Christian Geller, Lutz Eckstein, J. Marius Zöllner, Timo Woopen, Raphael van Kempen, Philip Schörner, Marc René Zofka
W11	Remote Operation Systems for Road Vehicles	Maytheewat Aramrattana, Andreas Riener, Andreas Schrank, Bengt Escher, Frank Diermeyer, Marek Vanzura, Michael Oehl, Ole Hans, Sanat Mharolkar, Yanbin Wu
W12	Disruptive Technologies for Intelligent Urban Traffic Monitoring and Network Management	Hao Yang, Harith Abdulsattar
W13	7th Workshop on Autonomous, Connected and Electrified Mobility Systems: Beyond Technical Silos	Mauro Salazar, Maria Laura Delle Monache, Raphael Stern

W14	Low-altitude Transportation Systems: Modeling, Operations, and Policy	Shaocheng JIA, Xiqun (Michael) Chen, Xin PEI, Kaidi Yang, Kai Wang, Qing-Long Lu
W15	Automated Mobility in Mixed Traffic – Toward Robust, Human-Centric, and Trustworthy Systems	Yiyun Wang, Yongqi Dong, Saeed Rahmani, Zhe Fu, Francesco Flammini, Xin PEI, Haneen Farah, Sergio Grammatico
W16	5th workshop on Intelligent Vehicle Meets Urban: Safe and Certifiable Navigation for Intelligent Vehicles in Complex Urban Scenarios	Daniel Medina, Li-Ta Hsu, Weisong Wen, Haoming Zhang
W17	Advances in Designing and Evaluating AI-empowered Human-Automated Vehicle Interaction	Xiaocong Zhao, Haoyang Liang, Yiru Liu, Zirui Li, Patrick Ebel, Haotian Shi, Ostap Okhrin, Jian Su
W18	From Pilots to Policy: A Roadmap for Standardized CAV Operations Testing on Public Roads	Tolga Ercan, Zsolt Szalay
W19	Human-Centered Intervention and Cooperative Autonomy Across Mobility Domains: Bridging Ground Vehicles and Aerospace Systems	Takahiro Sasaki, Nicola Baresi, Christopher Bridges, Manabu Tsukada, Frank Flemisch, Andrea Turconi, Nicolo Bernardini, Sakura Akahoshi
W20	DriveX – Foundation Models for Autonomous Driving	Walter Zimmer, Rui Song, Zhiyu Huang, Ross Greer, Julie Stephany Berrio Perez, Lars Ullrich, Jiajie Zhang, Max Peter Ronecker, Chuheng Wei, Yun Zhang, Zewei Zhou, Tianhui Cai, Yifan Liu, Alina Roitberg, Daniel Watzenig, Jiaqi Ma, Holger Caesar, Mohan M. Trivedi, Alois Knoll
W21	Computational Models of Human Road User Behavior for Evaluation of Automated Vehicles	Arkady Zgonnikov, Luigi Pariota, Gustav Markkula, Johan Engström, Jonas Bärgrman
W22	Trustworthy AI for Traffic Operation and Control	Kaidi Yan, Jingyuan Zhou, Qiqing Wang, Qing-Long Lu, Sisi Jian, Xiao Wen, Kun Gao
W23	5th Workshop on Intelligent and Automated Waterway Transportation	Philipp Maximilian Sieberg, Hanna Krasowski, Kathrin Donandt, Frederic Etienne Kracht, Lars Andreas Lien Wenersberg
W24	Trajectory Data Camp 2026: Transforming Observations into Real-World Impact	Junyi Ji, Marcello Montanino, Gergely Zachár, Daniel Work, Cathy Wu, Biagio Ciuffo, Meng Wang
W25	Infrastructure-based Perception Systems	Simon Schäfer, Bassam Alrifae, Ignacio Alvarez, Ehsan Hashemi
W26	Integrated Last-Mile and Last-50-Foot: Mobility Solutions for People and Freight	Petros Ioannou, Evangelos Kaisar, Ali Karimoddini, Dimitrios Dimitriou
W27	Traffic Control Optimization for Smart Cities	Maria Chiri, Roberto Guglielmi, Gennaro Notomista
W28	Automated and Electrified Racing: Opportunities for Future Intelligent Vehicles	Mattia Piccinini, Mauro Salazar, Johannes Betz

Tutorials

The tutorial presentations are scheduled throughout the conference, **from 16 to 18 September 2026**.

The full list of tutorials is provided in the table below.

ID	Title	Proposers
T1	Bridging the Sim-to-Real Gap in Traffic Engineering: Integrating Traffic Signal Control and Reinforcement Learning	Ferdous Al Rafi, Longchao Da, Xuesong Zhou, Hua Wei
T2	New Advances in ADAS/ADS Systems Modeling and Simulation	David Kan, Xiaowei Shi, Ke Ma
T3	An Introduction to Autoware and Its Application Platforms	Alexander Carballo, Simon Thompson
T4	Securing AI-Enabled Autonomous Vehicles: Adversarial Attacks, Efficient Mitigation, and Virtual Testing	Nasser L. Azad, Pulei Xiong, Saeedeh Lohrasbi, Farid Mafi Shourestani, Samyar Goodarzi, Kimia Dinashi
T5	IEEE CSS TC on Smart Cities Tutorial Session: Challenges and Opportunities for ITS in Smart Cities	Mauro Salazar
T6	Joint traffic management and transit operations	George Gunter
T7	AI-Driven Traffic Optimization in Real-World Urban Environments: From prediction to Signal Control Intervention	Ismail Arai

Regular Papers

The regular papers accepted for presentation at the conference address a broad range of topics in Intelligent Transportation Systems, in line with the conference theme, “Innovative Solutions for Future Transportation.”

The main topics covered include:

- Advanced ITS Mobility Systems
- Air, Road, and Rail Traffic Systems
- Autonomous Vehicle Systems
- Cooperative and Connected Vehicles
- Cyber-Physical Systems and IoT
- Emerging ITS Technologies and Innovations
- Human Factors and Vehicle Interaction
- Infrastructure and ITS Technologies
- Intelligent Waterborne Systems
- ITS Field Tests and Implementation
- ITS Validation and Verification
- Logistics and Intelligent Freight
- Public Transport and Mobility Services
- Safety, Security, and Privacy
- Sensing, Perception, and Scene Understanding
- Traffic Data Analytics and Machine Learning

Accepted regular papers are included in the program as oral presentations at ITSC 2026. These papers, prepared in the IEEE double-column format and limited to 6 pages, with up to 2 additional pages subject to an extra fee, will be published in the conference proceedings in IEEE Xplore.

Invited Papers

As regular papers, also invited papers deal with several key areas of intelligent transportation Systems and are in accordance with the conference theme, “Innovative Solutions for Future Transportation.”

Accepted invited papers have the same format of regular papers and will be published in the conference proceedings in IEEE Xplore.

Accepted invited papers are associated with the Invited Sessions reported in the table below and are scheduled in the program of ITSC 2026 as oral presentations.

Title	Session Organizers
Intelligent Fault Monitoring, Diagnosis, Prognostics, and Maintenance of Railway Infrastructure and Equipment	Hongrui Wang, Alfredo Nunez, Xiaoxi Hu, Li Zhu, Tao Tang
Human-in-the-Loop Autonomous Systems: Engineering Advances, Human Factors, and Trust-Aware Design	Yukun Lu, Yunzhijun Yu, Keqi Shu, Mingjian Wu, Luis Miranda-Moreno
Control, Communication, and Emerging Technologies in Smart Rail Systems	Li Zhu, Xiaoxi Hu, Alfredo Nunez, Hongrui Wang, Zhenzhen Jin, Jin Liu, Tao Tang
Human Factors and Human–Vehicle Interaction in Intelligent Vehicles	Cristina Olaverri-Monreal, Juan Felipe Medina-Lee
Next-Generation Autonomous Driving Systems: Self-Evolving Decision-Making, End-to-End Architectures, and Data-Driven Evaluation	Yukun Lu, Shuo Yang, Zirui Li, Rui Song, Yanjun Huang
Generative AI-Enabled Multimodal Mobilities for Future Hybrid Transportation Systems	Yang Xing, Chen Lv, Meng Wang, AnhTu Nguyen
Understanding, Diagnosis, and Verification of Learning-Based Autonomous Driving Systems	Meng Li, Shiyong Dong, Haoxuan Dong, Jincheng Hu, Zhang Yuanjian
Foundation Model-Empowered Decision-making and Planning for Intelligent Mobility Systems	Zirui Li, Haohan Yang, Wenhui Huang, Yangang Ren, Lei Yang, Xiaocong Zhao, Xiaolin He, Yunlong Lin, Chen Lv
Intelligent Integrated Airspace and Air Traffic Management for Future Air Transportation	Duc-Thinh Pham, Zhi Jun Lim, Yicheng Zhang
Trustworthy AI for Traffic Sensing and Control (The 2nd Edition)	Kaidi Yang, Jingyuan Zhou, Qiqing Wang, Jinhao Liang, Qing-Long Lu, Shaocheng Jia
Cybersecurity, Trust, and AI Reliability in Intelligent Transportation Systems	Gaetano Perrone
Traffic Control and Connected Autonomous Vehicles: benefits for efficiency, safety and beyond (4th edition)	Giacomo Basile, Cecilia Caterina Pasquale, Alberto Petrillo, Simona Sacone, Stefania Santini, Silvia Siri,
Strategic E-Mobility Planning Under Deep Uncertainty: Scenarios, Data-Driven Methods, and Policy Alignment	Jonas Mårtensson, Anna Pernestål, Sida Jiang, Henrik Svärd, Ehsan Saqib, Gyöző Gidofalvi, Jiali Fu, Zhenliang Ma, Lei Chen, Gabrijela Obradovic
Computational Models of Human Road User Behavior for Evaluation of Automated Vehicles	Arkady Zgonnikov, Luigi Pariota, Gustav Markkula, Johan Engström, Jonas Bårgman

Automated Vehicles at the Limits: Lessons and Opportunities from the Racetrack	Mattia Piccinini, Mauro Salazar, Johannes Betz
World Models for Safe and Scalable Autonomous Vehicles	Xintao Yan, Jiawei Wang, Shengbo Eben Li, Hongyang Li, Shuo Feng, Lingxi Li, Henry X. Liu
Control and Intelligent Technologies for X-by-Wire-Chassis Heavy-Duty Vehicles	Bo Leng, Lu Xiong, Felipe Jiménez
Virtual Validation for Intelligent Transportation Systems: A Holistic Perspective	Nick Schade, Cindy Demuth, Juergen Pannek
Invited Session on Intelligent and Automated Waterway Transportation	Philipp Maximilian Sieberg, Hanna Krasowski, Kathrin Donandt, Frederic Etienne Kracht
Bridging Optimal Control and Learning for Connected and Automated Vehicles	Jianye Xu, Bassam Alrifaaee, Andreas Malikopoulos, Amr Alanwar, Chen Lv, Ehsan Hashemi, Javier Alonso-Mora, Johannes Betz, Rahul Mangharam
Stability-Aware and Scalable Learning-Enabled Control for Cooperative and Connected Vehicles	Sheida Nozari, Alessio Iovine, Ali Krayani
AI-Enabled Data-Driven Modeling, Prediction, and Decision Support for Urban Mobility Systems	Hossein Nick Zinat Matin, Mostafa Ameli, Negin Alisoltani, Xuesong Zhou
Novel Electric Mobility Service Applications for Power Grid Flexibilization in Smart Cities	Andrea Bonfiglio, Antonella Ferrara, Silvia Siri, Jelena Stojkovic Terzic
AI-Empowered Automated Driving in Mixed Traffic	Yongqi Dong, Shen Wang, Li Li, Yongfu Li, Miguel A. Sotelo

Journal Presentations

Journal presentations are given by authors who have recently published research in IEEE journals related to Intelligent Transportation Systems and wish to present and discuss their work at the Conference. This track provides a valuable opportunity to showcase recently published research to an international audience of ITS researchers and professionals.

Each accepted journal presentation has been scheduled as part of an oral session at ITSC 2026. Since the corresponding paper has already been published in an IEEE journal, it will not be included in the conference proceedings.

Industry Track Contributions

The industry track contributions are intended for companies, technology providers, and innovators demonstrating real-world solutions, deployed systems, and industry-driven advancements in Intelligent Transportation System technologies.

Each accepted industry track contribution has been scheduled as part of an oral session at ITSC 2026.

The accepted contributions will not be included in the conference proceedings, but they will be disseminated in a dedicated section of IEEE Discovery. Authors of selected high-quality papers will be invited to submit extended versions of their work to a special track of the IEEE Intelligent Transportation Systems Magazine, which will be organized after the conference.

Late Breaking Results

A Poster Session is organized to showcase recent findings and ongoing research in the field of Intelligent Transportation Systems. It provides an excellent opportunity for authors to present their work, engage with the ITS community, and receive valuable feedback before submitting it for formal publication.

These contributions will be presented as posters during ITSC 2026 and will not be included in the conference proceedings.

Pre-Recorded Presentations

For participants who are unable to attend the conference in person, the oral presentation is changed in a pre-recorded presentation format. The 15-minute video is uploaded in the InfoVaya platform and is available for all attendants.

ITSC 2026

Technical Program

Program at a Glance

A full overview of the entire ITSC 2026 program across all four days, including workshops, technical sessions, and social events can be found below.

Program IEEE ITSC 2026

Time		15 September WORKSHOP DAY	16 September DAY 1	17 September DAY 2	18 September DAY 3
08:30 - 9:00	REGISTRATION	MORNING WORKSHOPS	OPENING		TECHNICAL SESSIONS
09:00 - 10:00	REGISTRATION		PLENARY LECTURE 2		
10:00 - 10:30	REGISTRATION		TECHNICAL SESSIONS		
10:30 - 11:00	REGISTRATION		COFFEE BREAK		
11:00 - 11:30	REGISTRATION	COFFEE BREAK	COFFEE BREAK	COFFEE BREAK	COFFEE BREAK
11:30 - 12:30	REGISTRATION	LUNCH WORKSHOPS	ITSS-ITE Forum	TECHNICAL SESSIONS	TECHNICAL SESSIONS
12:30 - 13:00	REGISTRATION		TECHNICAL SESSIONS	VISLAB PLENARY PRESENTATION	TECHNICAL SESSIONS
13:00 - 14:00	REGISTRATION	LUNCH	LUNCH	LUNCH	LUNCH
14:00 - 15:00	REGISTRATION	LUNCH WORKSHOPS	ITSS AWARDS	PLENARY LECTURE 3	TECHNICAL SESSIONS
15:00 - 16:00	REGISTRATION	BREAK	TECHNICAL SESSIONS	TECHNICAL SESSIONS	TECHNICAL SESSIONS
16:00 - 16:30	REGISTRATION	AFTERNOON WORKSHOPS	COFFEE BREAK	COFFEE BREAK	COFFEE BREAK
16:30 - 17:00	REGISTRATION		POSTER SESSION 1	POSTER SESSION 2	POSTER SESSION 2
17:00 - 17:30	REGISTRATION		TECHNICAL SESSIONS	TECHNICAL SESSIONS	TECHNICAL SESSIONS
17:30 - 18:00	REGISTRATION		TECHNICAL SESSIONS	TECHNICAL SESSIONS	TECHNICAL SESSIONS
18:00 - 19:00			A night with the coach	BUS TRANSFER FROM 17:45	FAREWELL
19:00 - 23:00		ROYAL WELCOME		UNDER THE NEAPOLITAN STARS GALA DINNER BY THE SEA	

Infovaya

You can browse the detailed ITSC 2026 conference program by selecting the “Program” button on the official InfoVaya event page:

<https://events.infovaya.com/event?id=179>

YP and WIE Event

The event organized by the IEEE ITSS Young Professionals & Women Committee for ITSC 2026 is entitled “Intelligent Mobility Systems: A Workshop for Emerging Engineers - Opportunities and Challenges” and is dedicated to innovation, ideas, and the future of intelligent mobility.

The event is scheduled on **16 September 2026** and consists of two main sessions.

Session I - Afternoon Program

15:00 – 15:05: Kick-off and welcome: introduction to the event and the coaching team.

15:05 – 15:30: Panel session [Gianmarco Montanari – General Director of Fondazione MOST]

15:30 – 15:55: Panel session [Mauro Salazar – Professor Eindhoven University]

15:55 – 16:00: Interactive activities

16:00 – 16:30: Refreshment break

16:30 – 16:40: Introduction to the Round Table

16:40 – 17:20: Round Table and Q&A [Ennio Adinolfi (Chief Executive Officer – Minervas), Negin Alisoltani (Assistant Professor, Université Gustave Eiffel); Chiara Colombaroni (Prof, Roma Sapienza University), Arnaud de La Fortelle (ITS Society BoG member, École des Mines de Paris - l'Université PSL and Heex Technologies), Erjen Lefeber (Professor at Eindhoven University of Technology), Ivan Moroni (CEO of TOKBO), Jeroen Ploeg (Lead Control Architect 2getthere), Agata Quattrone (Innovation Manager – Head of Digital Innovation & Sustainability - Almaviva s.p.a.), Meng Wang (Prof TU Dresden)]

17:20 – 17:55: 3 MT Thesis Competition: introduction & pitch of the 6 finalists

17:55 – 18:00: Closing remarks

Session II – Evening Program

18:00 – 22:30

Night with Coaches: an evening of reflective practice, group discussions, and networking with co-chairs and roundtable members. During this session, the winners of the 3 Minutes Thesis Competition will be announced.

IEEE ITSS-ITE Joint Forum on Infrastructure Support and Safety for Connected and Automated Transportation

The Forum on Infrastructure Support and Safety for Connected and Automated Transportation is organized jointly the IEEE Intelligent Transportation Systems Society (ITSS) and the Institute of Transportation Engineers (ITE). All registered ITSC Conference participants are invited to attend this forum.

The event is scheduled on **16 September 2026** and consists of two main sessions.

Session 1: Integrated Safety for Connected and Automated Transportation: From V2X Deployment to Infrastructure-Ready Automation

11:30 to 13:00

Focusing on infrastructure support for connected and automated vehicles, this session brings together leaders from ITE, IEEE, industry, and public agencies to examine how infrastructure investments and connected vehicle technologies can enable safer and integrated transportation systems. Building on prior discussions of V2X deployment and automated driving, panelists will explore how physical and digital infrastructure supports both near term safety applications and long term automated driving integration. Topics include V2X deployment, cooperative vehicle infrastructure systems, standards, and system level considerations for reliable operation in mixed traffic environments. The discussion will highlight key technical, institutional, and policy challenges to infrastructure supported CAV deployment, along with strategies to address them. The session aims to bridge technology and infrastructure perspectives and provide a unified view of how transportation systems can evolve to support safer, more predictable, and resilient mobility.

Session Chair: Petros Ioannou, President, IEEE ITSS

Presentations

- Report on US efforts on infrastructure support for CAVs, Jeff Lindley, Senior Advisor and Past Deputy Executive Director, ITE
- “Connected Automated Vehicles/Connected Interoperability (CAV/CTI) Activities”, Matt Mardy (ITE), Deputy Executive Director, Institute of Transportation Engineers, (ITE)
- Tim Leinmueller, Senior Technical Manager, DENSO AUTOMOTIVE Deutschland GmbH (TBC)

Panel Discussion: Gaps in and opportunities for infrastructure support for CAV

- Christoph Stiller (Karlsruher Institut für Technologies)
- Arnaud de La Fortelle (IEEE ITSS BoG member)
- Nobuyuki Ozaki VP Technical Activities
- Wei-Bin Zhang (IEEE ITSS Bog Members)

Session 2: Round Table Discussion: Opportunities for Collaboration Between ITE and IEEE

15:00 to 16:30

This round table discussion session intends to facilitate a dialog between ITSS and ITE leaderships to identify and advance opportunities for meaningful collaboration under the ITE–IEEE partnership. The session will follow the discussion at ITE annual meeting, focusing on developing actionable strategies across areas of shared interest and exploring joint initiatives such as co-sponsored

research, technical committees, standards development, conferences, and knowledge-sharing platforms.

Invited discussants include representatives from ITE and ITSS, as well ITSS leadership. The discussion will take place as a dialog on the opportunities for collaboration between IEEE, ITE and other international organizations concrete next steps to further the development of the infrastructure to support CAVs deployment.

Discussants from ITE

- Matt Mardy, Deputy Executive Director
- Jeff Lindley, Past Deputy Executive Director

Discussants from IEEE ITS Society:

- Petros Ioannou, President, University of Southern California
- Ljubo Vlacic, Past President, Griffith University
- Wei-Bin Zhang, BoG member, University of California at Berkeley
- James Misener, ITSS BoG member, WSB
- Arnaud de La Fortelle, BoG Member, ITSS
- Nobuyuki Ozaki, VP Technical Activities, Nagoya University
- Christoph Stiller, Karlsruher Institut für Technologies
- Members BoG and EXCOM

IEEE ITSS Hackathon @ITSC2026

The IEEE ITSS Hackathon themed around “ITSS Smart Mobility Data Challenge” is intended for innovators, students, professionals, and ITS enthusiasts. Attendance is limited to the first 100 registrants to ensure a high-quality experience. The IEEE ITSS Hackathon has been scheduled on **18 September 2026, from 09:00 to 13:00**.

The aim is to actively engage event participants in a 4-hour data-centric competition. Leveraging the power and scalability of AWS Cloud services, participants (students, PhD students, experts) will tackle real-world challenges on urban mobility issues.

The competition is designed to be highly inclusive, requiring no advanced programming skills but focusing on data analysis and the optimization of specific KPIs. Teams will use visual analysis tools and computing environments provided by AWS to explore a heterogeneous “Data Hypercube” and propose solutions that will be automatically evaluated by a scoring system, with rankings updated in real time.

The “ITSS Smart Mobility Data Challenge” focuses on challenges such as:

- Local Public Transport (LPT): Definition of the network structure: routes, stops, scheduled bus and underground timetables.
- Road Traffic: Aggregated and anonymized GPS data from fleets (e.g. taxis, logistics) to map average speeds and congestion levels on the road network.
- Micro-mobility: Create and implement enhanced strategies for mitigating environmental damage.

The scoring system is the heart of the competition, designed to eliminate the need for a jury and rely on objective optimization, as per the requirements. It is based on the following concepts:

- Participants do not submit code, but rather the solution (e.g., a list of coordinates, a schedule matrix).
- The solution is sent to an endpoint that performs a “simulation”.
- The simulator calculates the score (the KPI) and returns it.
- A Live Leaderboard shows the rankings in real time. The winner is whoever gets the best score in the shortest time (used as a tiebreaker).

IEEE will award prizes to the top three teams and additional recognition includes IEEE ITSS Certificates for all participants.

1st Prize: A prestigious IEEE ITSS Travel Grant to attend the IEEE ITSC 2027 conference in Boston, United States (September 2027). This is your ultimate ticket to network with global leaders in intelligent transportation systems + 400€ in AWS credits

2nd Prize: A €300 cash prize, proudly powered by the Scuola Politecnica e delle Scienze di Base, University of Naples Federico II + 300€ in AWS credits

3rd Prize: €300 in AWS credits

VisLabLunch @ITSC2026: where Autonomous Driving Meets Naples



VisLab, a global center of excellence for autonomous driving based in Parma and the technological heart of Ambarella (a NASDAQ-listed semiconductor leader from Silicon Valley), is delighted to host an exclusive lunch dedicated to the PhD community at IEEE ITSC 2026.

This lunch, scheduled on **17 September 2026**, is specifically intended for PhD students or young researchers passionate about autonomous cars, environmental perception, and intelligent systems. To ensure an intimate and high-quality networking experience, the event is limited to the first registered 100 PhD students.

This isn't just a lunch—it's your gateway into the world of industrial innovation:

- **Meet a Visionary:** Engage directly with Alberto Broggi, Founder and General Manager of VisLab and Past President of the IEEE Intelligent Transportation Systems Society (ITSS). Connect with a leader who has pioneered the development of autonomous vehicles globally.
- **From Lab to Road:** Discover how cutting-edge academic research scales into advanced AI processors and ADAS systems powering the next generation of self-driving cars.
- **Career & Vision:** Explore the unique synergy between Italian engineering creativity and the fast-paced environment of Santa Clara's Silicon Valley.

DEMO @ITSC2026

Miniature Testing of Dynamic, Connected, and Intelligent Applications: Video Demonstration of Scaled Vehicles



CARISSMA
Automotive
Safety Research

As the cost of testing novel applications continues to rise, the demand for extensive testing is increasing every day. While renting full-size test tracks is one option, we must explore alternatives to reduce the effort involved.

We present a connected vehicle fleet that consists of one 1:3.33 scaled Renault Megane and four 1:5 scaled Tesla Model 3 vehicles. The larger vehicle is highly over-actuated, allowing it to steer, brake, and accelerate all four wheels independently, to enable high-definition vehicle dynamics control testing. In contrast, the four smaller cars are designed more like conventional vehicles, with steering limited to the front axle and a focus on cooperative driving and risk-based decision-making.

Additionally, a seamless connection between the CARLA simulator and the perception systems of all fleet vehicles enables augmented testing, while real world factors and dynamics still apply. This approach reduces the need for a fully scaled-down testing environment; a simple parking lot can suffice!

Presenters:

- Jonas Bauernfeind, Technische Hochschule Ingolstadt
- Christian Birkner, Technische Hochschule Ingolstadt, who will be joining us online, streaming from the CARISSMA Indoor testing facility and showing one fleet vehicle in action

Event Schedule: during breaks

DEMO @ITSC2026

The Seamless Mobility of the Future: LIVE DEMO of Intelligent Intersections



ALMA MATER STUDIORUM
UNIVERSITÀ DI BOLOGNA

This live demonstration showcases four 1:10 scale cooperative, connected, and autonomous vehicles operating seamlessly on a figure-eight track with a central intersection.

Each vehicle is equipped with wireless communication capabilities based on ITS-G5 technology operating in the 5.9 GHz band. Vehicles periodically exchange status information with a centralized controller, which computes optimal crossing strategies and sends coordination commands in real time. This setup enables vehicles to traverse the intersection at regulated speeds without stopping, ensuring both safety and efficiency, and demonstrates the impact of communication and coordination on future cooperative mobility services.

Presenters:

- Lorenzo Farina, Vittorio Todisco, and Alessandro Bazzi, University of Bologna

It derives from a collaboration involving:

- Matteo Piccoli and Vittorio Di Paolo, CNIT WiLab

- Paolo Burgio, Carlo Augusto Grazia, Federico Gavioli, Salvatore Iandolo, Francesco Moretti, and Antonio Solida, University of Modena and Reggio Emilia
- Claudio Casetti, Marco Rapelli, and Francesco Raviglione, Politecnico di Torino

Event Schedule: 15:00 to 17:30, 17 September 2026

DEMO @ITSC2026

The Road to Remote Vehicle Operation - Development Roadmap and Live Demonstration



TECNOCAD

Discover the future of remote mobility! This session presents Tecnocad's platform connecting fleet management and remote vehicle operation, achieving low-latency remote control with round-trip times as low as 144ms over 5G. The session closes with a live demonstration: from Naples, the presenter connects in real time to ADONE, our autonomous vehicle in Turin, showing remote connection, status monitoring, and teleoperation over live network conditions.

Tecnocad's autonomous driving stack, built on Autoware, runs on two complementary layers: fleet management, handling vehicle status, mission assignment, and daily operations; and remote operation, giving human oversight when a vehicle hits edge cases, degraded conditions, or needs teleassistance. Our platform ties both together — architecture, data visualization, and a remote-operation workflow engineered around low-latency, real-time performance. An edge-computing design keeps critical processing close to the vehicle, minimizing round-trip delay, while compute placement, video/control-channel prioritization, and fallback behavior under degraded connectivity ensure the system stays safe and responsive even when network conditions vary. The result is a single platform taking autonomous vehicles from monitored fleets to human-in-the-loop remote control, tested live between two cities.

Presenters:

- Matteo Barale, CIO of Tecnocad
- Tianming Qu, Tech Leader of Tecnocad Autonomous team

Event Schedule: 15:30 to 16:00, 18 September 2026

Talent Portal & CV Booklet @ITSC 2026: Connecting Research Excellence with Industry Leaders & Academic Institutions

The IEEE ITSC 2026 Talent Portal is an initiative to bridge the gap between high-caliber researchers and the world's leading recruiters. The CV Booklet is a gateway to global visibility for those who are looking both for a pivotal role in industry and for the next tenure-track position in academia.

For Candidates: Industrial & Academic Career Paths

Showcase your research and technical expertise to both corporate innovators and top-tier university search committees.

- **Global Visibility:** Your profile will be distributed to leading academic, industrial participants and sponsors of the IEEE ITSC 2026 conference.
- **Dual-Track Opportunities:** Get noticed for R&D roles, post-doctoral fellowships, or Assistant Professor openings.
- **Targeted Networking:** Be invited to informal "Coffee meetups" or interviews during the conference at ITSC 2026 Talent Booth.

For Recruiters: Industry & Academia

Access a pre-vetted database of specialized talent in the ITS field.

Industrial Partners:

- **Efficient Scouting:** Browse the CV Booklet categorized by technical skills and graduation year.
- **Early Access:** Identify top-tier talent before they hit the open job market.
- **Onsite Interviews:** Reserve a "Talent Booth" space for private interviews.

Academic Institutions & Research Labs:

- **Faculty Recruitment:** Find the next generation of researchers for your PhD programs or faculty vacancies.
- **Collaborative Matching:** Connect with researchers whose expertise aligns with your lab's current funding and projects.
- **Direct Outreach:** Contact candidates specifically interested in staying within the academic track.

ITSC 2026

Social Program

Royal Welcome



The IEEE ITSC 2026 Welcome Reception will be held in the magnificent Royal Palace of Naples (Palazzo Reale), one of the city's most iconic landmarks and a symbol of its rich historical and cultural heritage.

Located in the heart of Piazza del Plebiscito, the Royal Palace has been the residence of kings, viceroys, and sovereigns for more than four centuries. Its monumental architecture, elegant courtyards, and beautifully preserved Royal Apartments offer an extraordinary setting where history, art, and culture come together.

The evening will begin with an exclusive guided tour of the Royal Palace, allowing participants to discover its magnificent ceremonial halls, priceless works of art, refined furnishings, and remarkable architectural details. This cultural experience offers a unique opportunity to appreciate one of Italy's most significant historic residences while immersing yourself in the artistic legacy of Naples.

Following the guided visit, guests will gather for the Welcome Reception, where they will have the opportunity to reconnect with colleagues, meet new members of the Intelligent Transportation Systems community, and establish collaborations in a relaxed and inspiring atmosphere. Guests will enjoy a selection of Italian specialties, accompanied by local wines and refreshments, offering a true taste of the region's renowned culinary tradition.

We are delighted to welcome you to this unforgettable opening event, where the timeless beauty of the Royal Palace provides the perfect backdrop to the beginning of IEEE ITSC 2026.

Meeting date: 15/09/2026

Meeting time: 19:00

Venue: Royal Palace of Naples (Palazzo Reale), Piazza del Plebiscito, Naples

Entrance: Access to the event is through the main entrance of the Royal Palace, located on Piazza del Plebiscito.

Admission: Access to the event is reserved for registered IEEE ITSC 2026 participants. Please bring and wear your IEEE ITSC 2026 conference badge, which is required for entry.

Under the Neapolitan Stars-Gala Dinner by the sea



The IEEE ITSC 2026 Gala Dinner will take place at Nabilah, an elegant seaside venue located along the coast of Bacoli, in the heart of the Phlegraean Fields. Surrounded by the beauty of the Mediterranean Sea, the venue offers a spectacular setting where crystal-clear waters, golden sunsets, and the relaxed atmosphere of the Neapolitan coastline create an unforgettable experience.

Nabilah is one of the most iconic beach clubs in southern Italy. Known for its refined atmosphere, elegant design, and breathtaking sea views, it perfectly combines Mediterranean charm and contemporary style. Just a short distance from Naples, it has become a landmark destination for unforgettable seaside events.

For centuries, the sea has shaped the identity of Naples, influencing its history, culture, and traditions. This unique coastal setting reflects the city's deep connection with the Mediterranean, offering participants an opportunity to experience one of the most captivating landscapes of Southern Italy, where nature, history, and hospitality come together in perfect harmony.

The evening will feature a refined culinary experience inspired by the flavors of Campania, showcasing fresh local ingredients, regional specialties, and the renowned hospitality of Southern Italy. Throughout the evening, participants will enjoy a selection of regional wines, live music, and a performance by the Scialapopolo, a traditional Neapolitan folk ensemble whose vibrant music and engaging performances celebrate the cultural heritage and festive spirit of Naples.

Set against the unique backdrop of the Neapolitan coastline, the Gala Dinner provides an elegant yet relaxed atmosphere in which participants can strengthen professional relationships, exchange ideas beyond the technical sessions, and experience the maritime spirit of Naples, where the beauty of the coastline, the richness of local traditions, and the warmth of Italian hospitality come together to create a truly memorable evening.

Meeting date: 17/09/2026

Meeting time: 17:45

Transportation: Shuttle buses will depart from the parking lot outside the Conference Venue-Stazione Marittima Building to Nabilah. Return shuttle service will be provided at the end of the event.

Venue: Nabilah, Bacoli (Naples)

Admission: Access is reserved for registered IEEE ITSC 2026 participants. Please bring and wear your IEEE ITSC 2026 conference badge, which is required for entry. Accompanying guests who reserved the event during the registration procedure have to hold a valid Gala Dinner ticket.

IEEE YP&WIE: Night with a Coach



The IEEE Young Professionals (YP) & Women in Engineering (WIE) Night with a Coach takes place in the vibrant heart of Naples, offering participants an opportunity to experience the city's extraordinary cultural heritage and world-famous culinary tradition while fostering professional networking in an informal setting.

The evening begins with a guided walking tour of the historic center of Naples, a UNESCO World Heritage Site recognized for its exceptional historical, artistic, and architectural significance. Accompanied by expert guides, participants will discover the city's unique urban fabric, where Greek, Roman, Medieval, Renaissance, and Baroque influences coexist within a living cultural landscape. Walking through its narrow streets and lively squares, they will encounter remarkable churches, historic palaces, monuments, and artisan workshops that have made Naples one of the most fascinating cultural capitals of the Mediterranean.

Following the guided tour, participants will continue the evening at Presepe Napoletano, one of the distinctive venues created by Gino Sorbillo to celebrate the traditions and identity of Naples. Nestled within the narrow, vibrant alleys of the city's historic center, just steps from the iconic Pulcinella Statue on Via dei Tribunali, the venue offers an authentic atmosphere where Neapolitan culture, history, and hospitality come together. These characteristic streets, alive with artisan workshops, historic buildings, and centuries-old traditions, capture the unique spirit of Naples and provide an unforgettable setting for this special evening.

The evening continues with an authentic Neapolitan experience, featuring the city's world-renowned pizza together with a rich selection of traditional local specialties and regional delicacies. Carefully prepared according to long-standing recipes and culinary traditions, these specialties offer

participants a genuine taste of Naples and Campania. In this unique setting, attendees will have the opportunity to continue conversations, exchange ideas, and strengthen professional connections while experiencing the warmth and conviviality that are hallmarks of Neapolitan hospitality.

By combining history, art, gastronomy, and professional interaction, the YP & WIE Night with a Coach reflects the unique spirit of Naples and offers participants an experience that extends well beyond the conference program.

Meeting date: 16/09/2026

Meeting time: 18:00

Meeting point: Conference Venue-Parthenope Building

Guided tour: Approximately 2 hours through the historic center of Naples

Neapolitan experience: pizza at Presepe Napoletano by Gino Sorbillo, Via dei Tribunali, Naples

Admission: Participation is reserved for attendees who have registered for the IEEE ITSC 2026 YP & WIE Event.

Farewell and Closing Ceremony



The ITSC 2026 Farewell and Closing Ceremony is a special occasion to celebrate the conclusion of the conference and its most outstanding achievements. It will be held on **18 September 2026**.

From 17:00 to 18:00 the **Closing Ceremony** will feature the final highlights of ITSC 2026, revisiting the most memorable moments of an inspiring week dedicated to innovation, research, and collaboration in Intelligent Transportation Systems. The program will also include the announcement of the Best Paper Award, the Best Student Paper Award, the Best ITSC 2026 Associate Editor Award, the Best ITSC 2026 Reviewer Award, the ITSC 2026 Hackathon.

From 18:00 to 19:00, following the Closing Ceremony, all participants are warmly invited to join the **Farewell Cocktail Reception**, a final opportunity to meet colleagues, celebrate the success of ITSC 2026, and say goodbye to Naples.

We look forward to sharing this special closing moment with the entire ITSC 2026 community!

ITSC 2026

Conference Awards

ITSS Awards

The ITSS Award Ceremony will take place on **16 September 2026, from 14:00 to 15:00**.

The ITSS President, Petros Ioannou, and the Vice Presidents for Educational Activities, Xiaopeng Li, Technical Activities, Nobuyuki Ozaki, Standards Activities, Meng Lu, Publication Activities, Yisheng Lv, and Administrative Activities, Yaobin Chen, will present the IEEE Intelligent Transportation Systems Society (ITSS) annual awards and introduce the recipients.

The following awards will be presented:

- **IEEE ITSS Best Dissertation Awards**
- **IEEE ITS Institutional Lead Award**
- **IEEE Outstanding ITS Research Award**
- **IEEE Outstanding ITS Application Award**
- **IEEE ITSS Young Researcher/Engineer Award**
- **IEEE ITS Lifetime Achievement Award**

ITSC 2026 Awards

The ITSC 2026 Award Ceremony will take place on **18 September 2026, from 17:00 to 18:00**.

The program will include:

- **Best Paper Award**, chaired by Alberto Petrillo
- **Best Student Paper Award**, chaired by Silvia Siri
- **Best ITSC 2026 Associate Editor Award** and **Best ITSC 2026 Reviewer Award**, chaired by Cecilia Caterina Pasquale
- **ITSC 2026 Hackathon Awards**, chaired by Bianca Caiazzo

Shortlisted papers for the Best Paper Award

Only papers with a student as the corresponding author are eligible for this award. The student must be enrolled in an academic institution at the time of submission. Co-authors can include faculty members and other researchers, but the primary contribution should come from the student.

To remain eligible for the award, the selected paper must be presented in person at the conference. We also kindly request that at least one of the authors attend the Award Ceremony, during which the winners will be announced.

The papers selected for the Best Paper Award are listed below.

Paper ID	Authors	Title
826	Suresh Purini, Archit Narwadkar, Deepak Gangadharan	From GPU to Microcontroller: Online Ridge Regression for Edge-Deployable Traffic Prediction
762	Toshiya Kitahara, Ryu Shirakami, Koh Takeuchi, Hisashi Kashima	CASTANET: Causality-Aware Spatio-Temporal Adversarial Network Using Traffic Incident Effects
1323	Muhammad Jahanzeb Khan, Samin Yasar, Mahmoud Nabil Mahmoud, Ahmad Alsharif	Mitigating Targeted Poisoning in Vehicular Federated Traffic Sign Classification Via KL-Divergence Detection
414	Arastoo Karimi Maskooni, Arash Hassani Barbin, Abrar Hazoor, Giuseppe Marinelli, Marco Bassani	Predicting Takeover Time in SAE Level 3 Driving at Freeway Merge and Diverge Ramps: Effects of Ramp Geometry and Driver Characteristics across Different Countries
264	Shunnosuke Koseki, Riki Kawase, Toru Seo	Wasserstein Distance-Based Rolling Horizon Control for Demand Responsive Transport under Uncertainty
1395	Abdulaziz Alhuraish, Yuhang Wang, Hao Zhou	Behavioral Risk Compensation in Human-AV Interactions: Asymmetric Cut-In Gap Acceptance from the Waymo Open Motion Dataset
781	Fei Chen, Huiying Fan	Resilience Evaluation of Coupled Power and Transportation Networks Considering Electric Vehicle Mobility

1256	Mohammad Elayan, Wissam Kontar	Behavioral Heterogeneity As Quantum-Inspired Representation
711	Kai-Fung Chu, Fan Ye, Chenchen Fan, Fumiya Iida	Reservoir Computing-Based Control of Traffic Emergent Behaviour
800	Chakming Liang, Ruoyao Li, Yafei Wang, Zexing Li, Mingyu Wu	Updating-Gaussian: Revisit Score Management Based Scene Updating for 3D Gaussian Splatting in Changing Environments
988	Sungyong Chung, Yanlin Zhang, Alireza Talebpour	OpenCF: A Standardized Benchmark for Car-Following Model Evaluation
1150	Ali Sabry, Aadila; Notomista, Gennaro	Stability of Differentially Flat Systems with Application to Newton-Raphson Tracking Control for Vehicle Dynamics

Shortlisted papers for the Best Student Paper Award

All papers submitted to the conference are eligible for this award. This includes papers authored by professionals, researchers, faculty members, industry practitioners, and students.

To remain eligible for the award, the selected paper must be presented in person at the conference. We also kindly request that at least one of the authors attend the Award Ceremony, during which the winners will be announced.

The papers selected for the Best Student Paper Award are listed below.

Paper ID	Corresponding Author	Other Authors	Title
1076	Kanak Mazumder	Fabian Flohr	LIE: LiDAR-Only HD Map Construction with Intensity Enhancement Via Online Knowledge Distillation
394	Riccardo Vianello	Matteo Pierini; Matteo Corno, Sergio M. Savaresi	Jerk-Constrained Speed Profile Generation for Autonomous Racing
385	Rania Benaissa	Antonyo Musabini, Rachid Benmokhtar, Philippe Xu, Xavier Perrotton	DG-BevGAN: Domain-Generalized BEV Image Synthesis Via Multi-Task Adversarial Learning
154	Till Beemelmanns	Shayan Sharifi, Manas Mehrotra, Ayushman Choudhuri, Lutz Eckstein	Towards Trustworthy and Explainable AI for Perception Models: From Concept to Prototype Vehicle Deployment
874	Chengran Yuan	Zijian Lu, Zhanqi Zhang, Yimin Zhao, Zefan Huang, Shuo Sun, Jiawei Sun, Jiahui Li, Christina Lee, Dongen Li, Songyi Xu, Mingyang Guan, Justin Yeoh, Chee-Meng Chew, Marcelo Ang	PIE: Perception and Interaction Enhanced End-To-End Motion Planning for Autonomous Driving

466	Roberto Brusnicki	David Pop, Yuan Gao, Mattia Piccinini, Johannes Betz	Can VLMs Unlock Semantic Anomaly Detection? a Framework for Structured Reasoning
821	Shubham Vaijanath Phoolari	Aleya Kara; Christoph Lauer, Steven Peters	Proposal-Conditioned Latent Diffusion for Closed-Loop Traffic Scenario Generation
386	Kaushik Bhowmik	Anne Spalanzani, Philippe Martinet	CG-MOVE: Candidate Graph Network for Multi-Agent Motion Forecasting Including Heterogeneous Vulnerable Agents
779	Xinghang Zhu	Luis Miranda-Moreno, Lijun Sun	Recovering Intrinsic OD Preferences in Bike-Sharing Systems Via Bayesian Gaussian Decomposition
1007	Christian Hürten	Dieter Schramm, Philipp Maximilian Sieberg	Recurrent Neural Network-Based Modeling of Inland Vessel Maneuvering Dynamics
1055	Juan Pablo Bertucci	Vincent Kuipers, Finn Vehlhaber, Mauro Salazar, Theo Hofman	Evaluating Electric Ground-Support Vehicle Control with Airport Digital Twins
1317	Zhiqing Zhang	Chong Wang, Wei Dong, Xiang Yan, Zhao Long, Zhengliang Cai, Xinya Sun	A Robust Optimization Method for Period Scheduling Plan of Railway Freight Marshalling Station Based on Ordinal Optimization
1348	Cameron Hickert	Shreyaa Raghavan, Cameron Hickert, Monica Chan, Cathy Wu	Dynamic Gradient-Based Calibration for Robust and Accurate Traffic Macrosimulation

ITSC 2026

Local Information

About Naples

Naples opens like an amphitheater on the sea, surrounded by Mount Vesuvius, the coastal mountains, and its surrounding islands. The city, placed at the center of the Mediterranean Sea and perennially sunny, is the capital of the Campania Region, and it is considered the cultural capital of Southern Italy.



Full of life and culture, Naples is one of the most beautiful cities in Italy, rich in arts and culture. Founded in the ancient Greco-Roman era, Naples is one of the most ancient cities in Europe, and, thanks to its rich multicultural background due to French, Spanish and Arabian dominations, the city is unique and contains plenty of UNESCO forts, castles, palaces, churches, monasteries, piazzas, galleries and museums to visit. Indeed, the current urban fabric preserves a selection of outstanding elements of its long and eventful history, as expressed in its street pattern, its wealth of historic buildings and parks, the continuation of many of its urban and social functions, its wonderful setting on the Bay of Naples and the continuity of its historical stratification.

The nearby areas, including the suggestive Sorrento and Amalfi coasts, as well as Capri, Ischia and Procida islands, are also just as enchanting thanks to their natural wonders and breathtaking views.

Finally, it is worth noting that Naples is also the city of pizza and of the most colorful and delicious Italian cuisine.

Further information: <https://www.visitnaples.eu/en>

Conference Venue

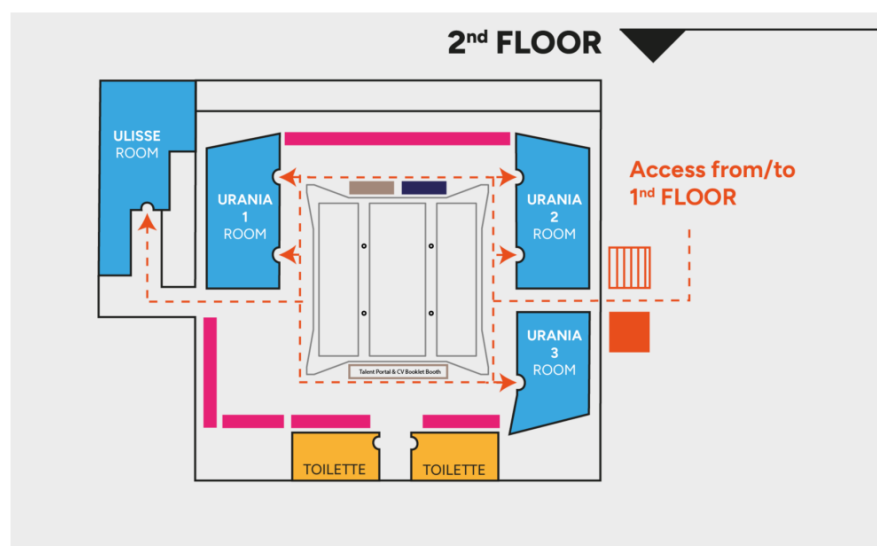
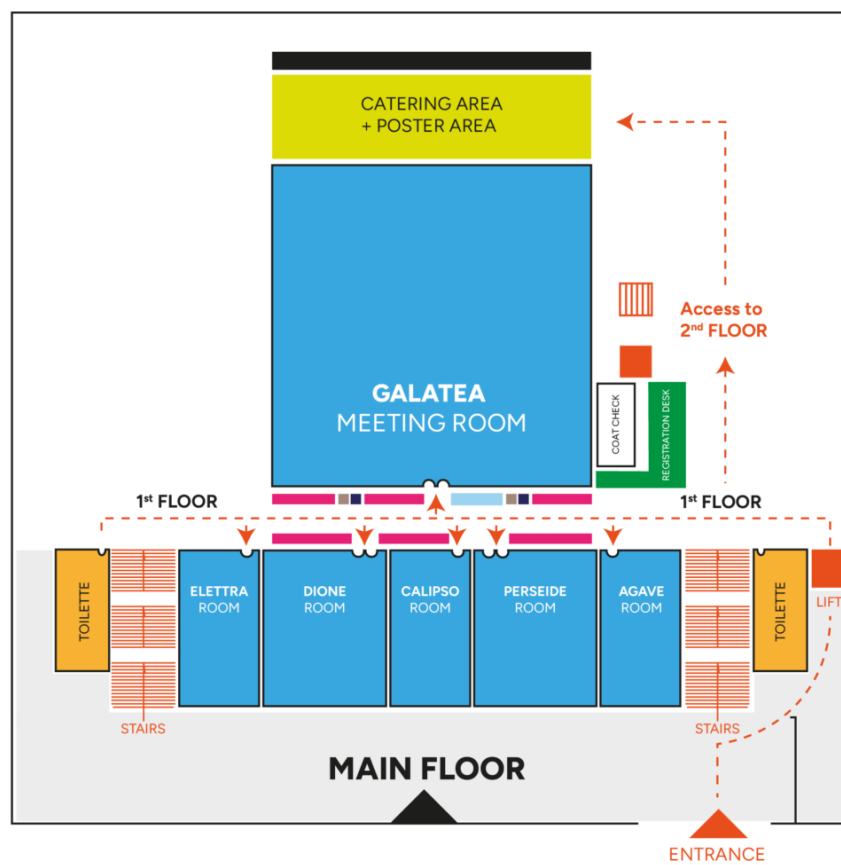
The venue of IEEE ITSC 2026 is the **Convention Bureau Stazione Marittima**, whose conference facilities are located in two adjacent buildings:

- the Stazione Marittima Building
- the Parthenope Building

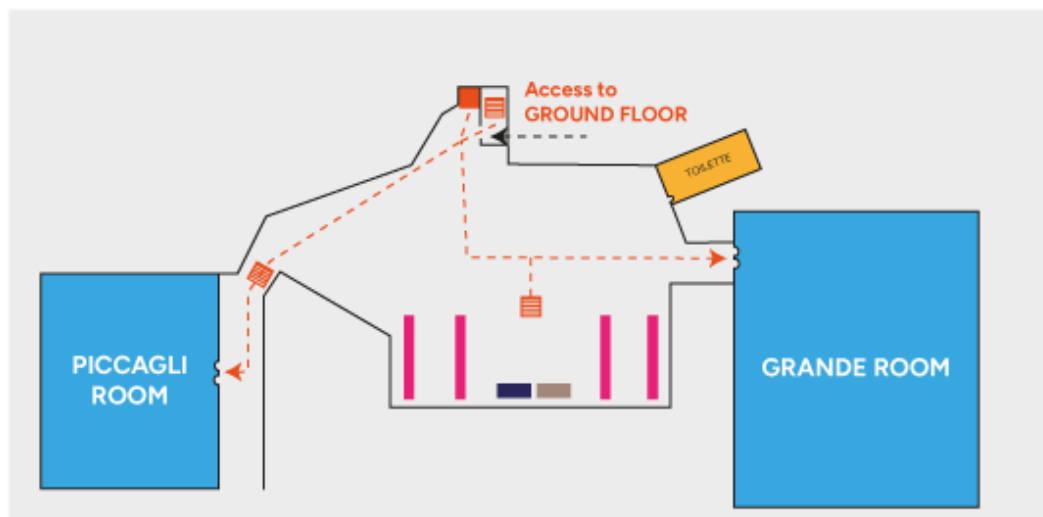
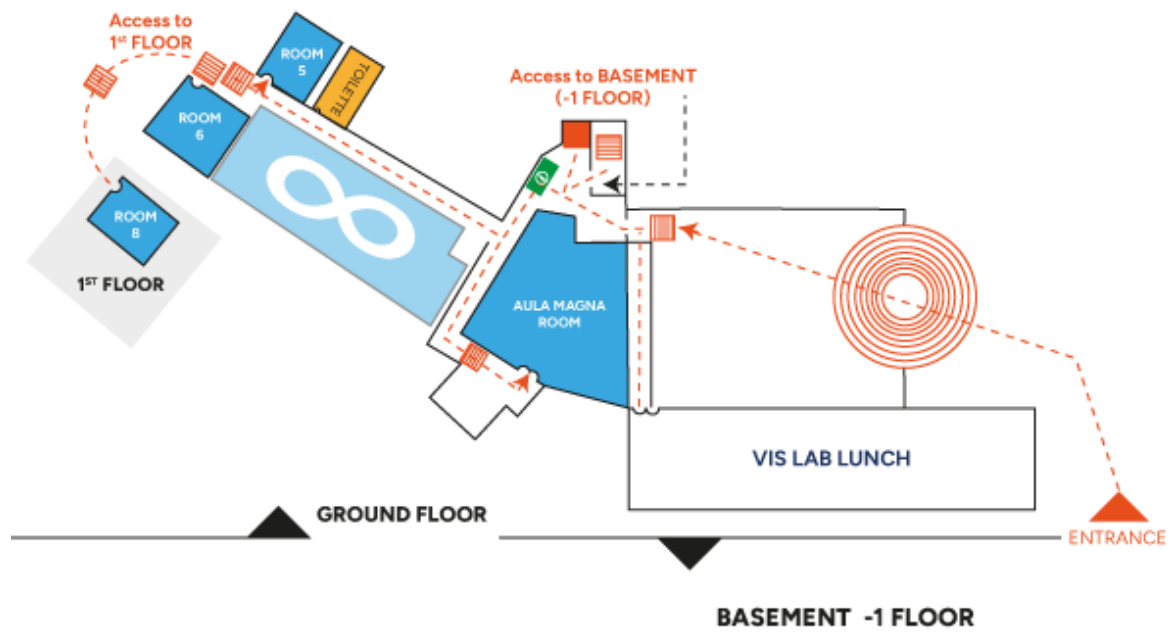
Technical sessions and conference activities will be held across both buildings, which are connected within the same venue.



STAZIONE MARITTIMA BUILDING



PARTHENOPE BUILDING



**FROM STAZIONE MARITTIMA BUILDING
TO PARTHENOPE BUILDING
TO ROYAL PALACE OF NAPLES**

